- 1. State true or false. Justify your answers.
 - (i) Suppose that A and B are nonsingular $n \times n$ matrices. Then A + B is nonsingular matrix.

Solution: False. If *A* is nonsingular then so is -A, but hen A - A = 0 is a singular matrix. \Box

(ii) Let *A* be an $n \times n$ matrix such that the sum of elements in each row of *A* is zero. Then *A* is a singular matrix.

Solution: True. Since the sum of elements in each row of A is zero, one of the columns (say n^{th} -column) can be written as linear combination of other columns. Thus, it is clear that A is a singular matrix.

Another way to prove this fact is as follows: Let *A* is nonsingular, also let us consider the vector $v = (1, \dots, 1) \in \mathbb{K}^n$. Then we have A.v = 0, which is in contradiction (since given that *A* is invertible, Ax = 0 has a unique solution for $x \in \mathbb{K}^n$).

(iii) Let $C[-\pi,\pi]$ be the vector space of all continuous functions defined on the interval $[-\pi,\pi]$. The subset $\{Cos(x), Sin(x)\}$ in $C[-\pi,\pi]$ is linearly independent.

Solution: True. Let $a_1, a_2 \in \mathbb{R}$ such that

$$a_1.Cos(x) + a_2.Sin(x) = 0.$$

Let $x = \pi/2$, then $a_2 = 0$.

Similarly, if x = 0, then $a_1 = 0$. Hence, $\{Cos(x), Sin(x)\}$ is linearly independent subset in $C[-\pi, \pi]$.

(iv) Let *A* be an $n \times n$ matrix. If $rank(A) \neq n$, then 0 is an eigenvalue of *A*.

Solution: True. Let us note that $rank(A) \neq n$ if and only if det(A) = 0 and det(A) is the product of eigen values of *A*. Therefore, if det(A) = 0, then 0 is an eigen value of *A*.

(v) Let A, B be $n \times n$ matrices with A invertible. Then nullity(AB) = nullity(B).

Solution: True. Let us note that since *A* is invertible, for any $x \in \mathbf{K}^n$, we have

$$Ax = 0$$
 if and only if $x = 0$.

Thus, ABx = 0 if and only if Bx = 0, which, in turn, implies that

nullspace(AB) = nullspace(B).

Hence, $\operatorname{nullity}(AB) = \operatorname{nullity}(B)$.

$$A = \begin{bmatrix} 1 & 1 & 2 & 3 \\ 3 & 4 & 1 & 2 \\ 1 & 2 & 5 & 4 \end{bmatrix}$$

(a) Find the solutions to the system of equations AX = 0.

Solution: Let us first change *A* into echelon form.

 $R_2 \rightarrow R_2 - 3.R_1, R_3 \rightarrow R_3 - R_1$

$$\sim \begin{bmatrix} 1 & 1 & 2 & 3 \\ 0 & 1 & -5 & -7 \\ 0 & 1 & 3 & 1 \end{bmatrix}$$

 $R_3 \rightarrow R_3 - R_2$

$$\sim \begin{bmatrix} 1 & 1 & 2 & 3 \\ 0 & 1 & -5 & -7 \\ 0 & 0 & 8 & 8 \end{bmatrix}$$

 $R_3 \rightarrow R_3/8$

$$\sim \begin{bmatrix} 1 & 1 & 2 & 3\\ 0 & 1 & -5 & -7\\ 0 & 0 & 1 & 1 \end{bmatrix}$$
$$X = \begin{bmatrix} x\\ y\\ z\\ w \end{bmatrix}.$$

Let

So, solutions of
$$AX = 0$$
 is given by the following expression.

$$\begin{bmatrix} 1 & 1 & 2 & 3 \\ 0 & 1 & -5 & -7 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = 0$$

Thus, solution is given by

$$(x, y, z, w) = \{k(-3, 2, -1, 1) : k \in \mathbb{R}\}$$

(b) Find a basis for the solution space of AX = 0.

Solution: Dimension of solution space = number of unknowns-rank(A)=1. Thus, basis for the solution space of AX = 0 is {(-3,2,-1,1)}.

- 3. Let P_3 denote the vector space of all polynomials with real coefficients of degree less than or equal to 3. Let $S = \{1 + x, 1 + x^2, x x^2 + 2x^3, 1 x x^2\}.$
 - (a) Show that *S* is a basis for P_3 .

Solution: Since number of elements in *S* is equal to the dimension of P_3 , it is enough to show that *S* is linearly independent set.

Let $a.(1 + x) + b.(1 + x^2) + c.(x - x^2 + 2x^3) + d.(1 - x - x^2) = 0$ i.e., $(a + b + d).1 + (a + c - d).x + (b - c - d).x^2 + (2c).x^3 = 0$ Writing the matrix form in terms of the standard basis $\{1, x, x^2, x^3\}$, we have

1	1	0	1]	$\begin{bmatrix} a \end{bmatrix}$	[0]
1	0	1	-1	b	_ 0
0	1	-1	-1	c	- 0
0	0	2	0	d	0
-			_		
		-			_

Let

$$A = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 1 & 0 & 1 & -1 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 2 & 0 \end{bmatrix}$$

Then using row transformations it follows that rank(A) = 4, i.e. there exists a unique solution given by a = b = c = d = 0. Hence, the set *S* is a basis for P_3 .

(b) Find the change of basis matrix with respect to the standard basis $\{1, x, x^2, x^3\}$.

Solution: Let us write the elements of the basis *S* in terms of the standard basis.

$$\begin{aligned} 1+x &= 1.(1)+1.(x)+0.(x^2)+0.(x^3)\\ 1+x^2 &= 1.(1)+0.(x)+1(x^2)+0.(x^3)\\ x-x^2+2x^3 &= 0.(1)+1.(x)+(-1)(x^2)+2.(x^3)\\ 1-x-x^2 &= 1.(1)+(-1)(x)+(-1)(x^2)+0.(x^3) \end{aligned}$$

Therefore, the change of basis matrix is given by

$$P = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 1 & 0 & 1 & -1 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 2 & 0 \end{bmatrix}$$

(c) Find the co-ordinate vector for the polynomial $f(x) = -3 + 2x^3$ in terms of the basis S. Solution: Let us write f(x) as a linear combination of the elements in *S*

$$f(x) = a.(1+x) + b.(1+x^2) + c.(x-x^2+2x^3) + d.(1-x-x^2) = 0.$$

i.e.,

$$-3 + 2x^{3} = (a + b + d).1 + (a + c - d).x + (b - c - d).x^{2} + (2c).x^{3}$$

On comparing both sides, we get following system of equations.

$$a + b + d = -3$$
$$a + c - d = 0$$
$$b - c - d = 0$$
$$2c = 2.$$

The solution of the above system is given by

$$c = 1, d = -1, a = -2, b = 0.$$

Thus, the co-ordinate of f(x) in terms of the basis *S* is given by

$$[f(x)]_S = \begin{bmatrix} -2\\0\\1\\-1 \end{bmatrix}.$$

4. Let W_1 be the space of $n \times n$ matrices with trace zero. Find a subspace W_2 of $\mathbb{R}^{n \times n}$ such that $\mathbb{R}^{n \times n} = W_1 \oplus W_2$.

Solution: Note that $W_1 = \{A = (a_{ij})_{1 \le i,j \le n} : \sum_{i=1}^n a_{ii} = 0\}$. Clearly, for a fixed $i \in \{1, 2, ..., n\}$, $a_{ii} = -\sum_{j \ne i} a_{jj}$. i.e.,

$$\dim(W_1) = n^2 - 1.$$

Let us define

$$W_2 = \{B = (b_{ij})_{1 \le i,j \le n} : b_{ij} = 0 \forall (i,j) \ne (1,1)\}.$$

It is clear that $W_1 \cap W_2 = \{0\}$. Now, let $C = (c_{ij}) \in \mathbb{R}^{n \times n}$. We define $A = (a_{ij}) \in W_1$, and $B = (b_{ij}) \in W_2$ such that C = A + B.

$$a_{ij} = c_{ij} \qquad \forall i \neq j;$$

$$a_{ii} = c_{ii} \qquad \forall i = 2, 3, \dots, n;$$

$$a_{11} = -\sum_{i=2}^{n} a_{ii};$$

$$b_{11} = -\sum_{i=1}^{n} a_{ii};$$

$$b_{ij} = 0 \qquad \forall (i, j) \neq (1, 1).$$

It immediately follows that C = A + B, i.e. $\mathbb{R}^{n \times n} \subset W_1 + W_2$. Therefore,

$$\mathbb{R}^{n \times n} = W_1 \oplus W_2.$$

5. (a) State and prove rank-nullity theorem for a linear transformation $T: V \to W$, where *V* is a finite dimensional vector space.

Solution: Let dim(V) = n, also let us fix a basis $\mathcal{B} = \{x_1, x_2, \dots, x_n\}$ of the vector space *V*. Let us assume that matrix of *T* with respect to the basis \mathcal{B} is given by $A = [T]_{\mathcal{B}}$. If rank(A) = n, then the only solution to AX = 0 is the trivial solution X = 0. Hence, in this case, nullspace(A) = 0, so nullity(A) = 0 and the following equation holds.

$$\operatorname{rank}(T) + \operatorname{nullity}(T) = n.$$

Here, we used the fact that rank(T) = rank(A), and nullity(T) = nullity(A).

Now, we assume that $\operatorname{rank}(A) = r < n$. In this case, there are n-r > 0 free variables in the solution to AX = 0. Let $t_1, t_2, \ldots, t_{n-r}$ denote these free variables (chosen as those variables not attached to a leading one in any row-echelon form of A), and let $X_1, X_2, \ldots, X_{n-r}$ denote the solutions obtained by sequentially setting each free variable to 1 and the remaining free variables to zero. Note that $\{X_1, X_2, \ldots, X_{n-r}\}$ is a linearly independent set. Every solution to AX = 0 is a linear combination of $X_1, X_2, \ldots, X_{n-r}$, i.e.,

$$X = t_1 \cdot X_1 + t_2 \cdot X_2 + \ldots + t_{n-r} \cdot X_{n-r},$$

which shows that the set $\{X_1, X_2, ..., X_{n-r}\}$ spans nullspace(A). Thus, the set $\{X_1, X_2, ..., X_{n-r}\}$ is a basis for nullspace(A), and nullity(A) = n - r. Therefore, the following equation holds.

$$\operatorname{rank}(T) + \operatorname{nullity}(T) = n.$$

(b) Let $T : V \to V$ be a linear operator on a vector space of dimension 2. Assume that T is not a multiplication by a scalar. Prove that there is a vector $v \in V$ such that $\mathcal{B} = \{v, T(v)\}$ is a basis of V, and describe the matrix of T with respect to the basis \mathcal{B} .

Solution: Let us assume that for each $v \in V$, the set $\{v, T(v)\}$ is linearly dependent. i.e., there exist $a, b \in \mathbb{K}$ not simultaneously zero such that

$$a.v + b.T(v) = 0.$$

Case 1. If $a \neq 0, b = 0$, then $a.v = 0 \ \forall v \in V$ implies that a = 0, which is in contradiction.

Case 2. If $a = 0, b \neq 0$, then $b.T(v) = 0 \quad \forall v \in V$ implies that $T(v) = 0 \quad \forall v \in V$, i.e., *T* is a multiplication by a scalar, which is in contradiction.

Hence, $a, b \neq 0$, which in turn, implies that T(v) = (a/b).v for all $v \in V$. Again, T is a multiplication by a scalar, which is in contradiction. Therefore, there exists a non-zero vector $v \in V$ such that $\{v, T(v)\}$ is a linearly independent set. So, \mathcal{B} is a basis of V.

Next, T(V) = 0.v + 1.T(v), and $T^2(v) = \alpha .v + \beta .T(v)$ for some $\alpha, \beta \in \mathbb{K}$. Thus, matrix of *T* is given as follows.

$$[T]_{\mathcal{B}} = \begin{bmatrix} 0 & \alpha \\ 1 & \beta \end{bmatrix}.$$

6. Define the map $T : \mathbb{R}^3 \to \mathbb{R}^3$ by

$$T\begin{bmatrix} x_1\\ x_2\\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 + x_3\\ x_2 + x_3\\ x_3 \end{bmatrix}.$$

(a) Find the matrix of T with respect to the standard basis.

Solution: Let us write the images of the elements in the standard basis S under the map T.

$$T(1,0,0)^{t} = (1,0,0)^{t}$$
$$T(0,1,0)^{t} = (1,1,0)^{t}$$
$$T(0,0,1)^{t} = (1,1,1)^{t}.$$

Then, matrix of T with respect to the standard basis S is given by

$$[T]_{\mathcal{S}} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}.$$

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(b) Find the matrix of *T* with respect to the basis $\mathcal{B} = \{(1,1,0)^t, (1,-1,0)^t, (-1,0,-1)^t\}$.

Solution: If $T(1,1,0^t) = a.(1,1,0)^t + b.(1,-1,0)^t + c.(-1,0,-1)^t$, then we get the following expression.

$$(2,1,0) = (a+b-c, a-b, -c).$$

Clearly, c = 0, a = 3/2, and b = 1/2. i.e.,

$$[T(1,1,0)^t]_{\mathcal{B}} = \begin{bmatrix} 3/2\\1/2\\0 \end{bmatrix}.$$

Similar calculation yields the following co-ordinates.

$$[T(1,-1,0)^t]_{\mathcal{B}} = \begin{bmatrix} -1/2\\1/2\\0 \end{bmatrix}$$
, and $[T(-1,0,-1)^t]_{\mathcal{B}} = \begin{bmatrix} -1\\0\\1 \end{bmatrix}$.

Therefore, the matrix of T with respect to \mathcal{B} is given as follows.

$$[T]_{\mathcal{B}} = \begin{bmatrix} 3/2 & -1/2 & -1 \\ 1/2 & 1/2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

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(c) Describe the null space and the range of *T*. Also find the rank and the nullity of *T*.Solution: Null space of *T* is given by

$$N(T) = \{ X \in \mathbb{R}^3 : T(X) = 0 \}.$$

i.e., for $X = (x_1, x_2, x_3)^t \in N(T)$, we have

$$T(x_1, x_2, x_3)^t = (x_1 + x_2 + x_3, x_2 + x_3, x_3)^t = (0, 0, 0)^t,$$

which implies that $x_1 = x_2 = x_3 = 0$. Hence, $N(T) = \{0\}$.

If range of *T* is denoted by R(T), then by Rank-Nullity theorem,

 $\dim(R(T)) = 3 =$ dimension of codomain.1

i.e., $R(T) = \mathbb{R}^3$. Moreover, rank of T = 3 and Nullity of T = 0.